# Minimum norm interpolation by perceptra: Explicit regularization and implicit bias

## Jiyoung Park<sup>1</sup> Ian Pelakh<sup>2</sup> Stephan Wojtowytsch<sup>3</sup>

<sup>1</sup>Department of Statistics Texas A&M University

<sup>2</sup>Department of Mathematics Iowa State University

<sup>3</sup>Department of Mathematics University of Pittsburgh

#### NeurIPS 2023

# Table of Contents



#### Introduction

- Motivations
- Preliminaries
- Main questions

# Main

- Notations
- General Convergence Result
- Numerical Experiments
- Conclusion & Further Works

# Appendices

- Proof sketches
  - $L^{p}(\mu)$  convergence
  - Minimum norm interpolation



Why we study a perceptron (Two-Layer neural network, shallow neural network, ...)?

- A tractable model for the theoretical analysis.
  - Implicit bias
    - How model settings (activation functions, optimization algorithms, initializations, ...) affect the solution we obtain?
    - Model settings 'implicitly' give us some 'bias' toward the certain solutions.
  - Depth separation
    - What kind of problems are solved with shallow networks, and better solved by deeper networks?

• A neural network is a function of the following form:

$$f(x) = g \circ h_K \circ h_{K-1} \circ \cdots h_1(x)$$

where  $h_k : \mathbb{R}^{d_{k-1}} \to \mathbb{R}^{d_k}$  s.t.  $h_k(z) = \sigma_k(W_k z + b_k)$ .

- W is called a 'weight'.
- b is called a 'bias'.

 $\bullet~\sigma$  is a pre-defined non-linear function called an 'activation function'.

- Examples: tanh(x),  $ReLU(x) = max\{0, x\}$ .
- From now on, we fix  $\sigma = \text{ReLU}$ .
- g is called a final layer, and convert the output into desired form (linear map if regression, softmax function if classification, ...).
- Each  $h_k$  is called a layer,  $d_k$  is called a width of the kth layer. K is called a depth.



- Why neural network? Universal Approximation Theorems.
  - Any continuous function with compact support can be approximated by a neural network with suitable width, depth, and activation w.r.t. sup-norm topology (i.e. a set of neural network is dense in C(K) w.r.t. sup-norm topology).
  - Limitations:
    - Compact support is necessary.
    - Lacking quantatitive bound or obtaining very loose bound.
    - Only for sup-norm topology.
- In shallow neural network cases, these limitations can be resolved.



• A Two-Layer neural network (perceptron, shallow neural network, ...) is the neural network with two layers including a final layer.

$$f_m(x) = \frac{1}{m} \sum_{j=1}^m a_j \sigma(w_j^T x + b_j).$$

- Which functions can be approximated well by a Two-Layer ReLU neural network?
  - A measure representation of *m*-width Two-Layer neural networks:

$$f_m(x) = \frac{1}{m} \sum_{j=1}^m a_j \sigma(w_j^T x + b_j)$$
$$= \int a\sigma(w^T x + b) d\left(\frac{1}{m} \sum_{j=1}^m \delta_{\theta_m}\right)$$
$$\Rightarrow f(x) = \int_{\theta} a\sigma(w^T x + b) d\pi(\theta)$$
(1)

where  $\theta = (a, w, b)$  and  $\pi(\theta)$  is a probability measure in  $\Theta$  space.

• Denote  $\mathcal{B}$ : a set of functions that can be expressed by the form (1).



• We can assign a natural norm in  $\mathcal{B}$  (Barron norm).

$$\|f\|_{\mathcal{B}} := \inf_{\pi} \int |a|(\|w\|+|b|)d\pi.$$

- The normed space  $(\mathcal{B}, \|\cdot\|_{\mathcal{B}})$  is indeed a Banach space.  $\Rightarrow$  'Barron Space'
- Barron space is a space can be approximated well by perceptra (i.e. perceptra is dense subset of Barron space w.r.t. Barron norm).

- Barron space has a relationship with other function spaces  $\rightarrow$  convenient theoretical analysis ([EW21]).
  - E.g.  $H^s(\mathbb{R}^d) \subseteq \mathcal{B}$  for s > d/2 + 2 if  $\mu$  has a bounded support.  $\mathcal{B} \subset C^{0,1}(\mathbb{R}^d)$ .
  - Intuition: The form in (1) with σ(·) = cos(·) is a ℝ-valued Fourier inversion → || · ||<sub>B</sub> resembles the fractional Sobolev norm.
  - $\Rightarrow$  Is everything good now?



- The existence of the bias term in Barron norm causes discrepancies with practical settings. Why?
  - Barron Norm: Not invariant under translations in the data space.
    - $\Rightarrow \Leftarrow$  In practice we frequently center the data.
  - Bias term has no contribution to overfitting.
    - ... Want to make a regularization without controlling the bias.
- Due to above facts, in practice 'weight decay' penalty is used instead of Barron norm penalty.

$$R_{WD}(\theta) = rac{\|a\|_{\ell^2}^2 + \|W\|_F^2}{2m}.$$

 $\Rightarrow$  Any concept corresponding to this Weight Decay regularizer?

• Construct continuum extension of Weight Decay regularizer:

$$[f]_{\mathcal{B}} = \inf_{\pi} R_{WD}(\pi) := \inf_{\pi} \frac{1}{2} \int |a|^2 + \|w\|^2 d\pi.$$

This  $[\cdot]_{\mathcal{B}}$  is not a norm but is a semi-norm.  $\Rightarrow$  'Barron semi-norm'.

- Benefits of Barron semi-norm:
  - Any f with f(0) < ∞ and [f]<sub>B</sub> < ∞ is a Barron function ⇒ Can import theoretical benefits of Barron norm.
  - If  $f \in \mathcal{B}$ , then  $Lip(f) \leq [f]_{\mathcal{B}}$ .
- Minimum norm interpolant: A function with min[f]<sub>B</sub> under data fitting constraint.



Main questions addressed in the work:

- Can we obtain the approximation error between a Two-Layer ReLU network and a target function in terms of number of parameters and data points, under more general conditions (unbounded & non-Lipschitz loss, non-compact & sub-Gaussian data)?
- How do Two-Layer ReLU networks interpolate where there is no data?
- Can we use theoretical solutions to compare different learning schemes (optimization algorithms, initialization)?



- n: Dataset size.
- m: Width of the neural network.
- $\lambda$ : Strength of weight decay regularizer in the risk functional.
- f\*: Target function.
- Two-layer ReLU net  $f_{\theta}(x) = \frac{1}{m} \sum_{j=1}^{m} a_j \sigma(w_j^T x + b_j)$
- (Regularized) empirical risk

$$\widehat{\mathcal{R}}_{n,m,\lambda}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} \ell^2 \left( f_{\theta}(x_i), \ f^*(x_i) \right) + \lambda R_{WD}(\theta)$$

- $f_n = \text{Empirical Risk Minimizer (ERM) for } \widehat{\mathcal{R}}_{n,m_n,\lambda_n}$ .
- $[\cdot]_{\mathcal{B}}$ : Barron semi-norm (infinite width weight decay norm).



## Theorem (Convergence Theorem)

If m and  $\lambda$  scale with n as

$$\frac{\log n}{\sqrt{n}} \ll \lambda \ll 1, \qquad \frac{1}{m} \ll \lambda,$$

then almost surely over the choice of data points,  $f_n$  converges to  $f_{\infty}$  (1) in  $L^p(\mu)$  for  $p < \infty$  and (2) uniformly on compact subsets of  $\mathbb{R}^d$ , where  $f_{\infty} \equiv f^* \mu$ -almost everywhere and  $[f_{\infty}]_{\mathcal{B}} \leq [f^*]_{\mathcal{B}}$ . Also, with probability  $1 - 1/n^2$ :

$$\begin{split} \|f_{(a,W,b)_n} - f^*\|_{L^2(\mu)}^2 &\leq C \bigg( \frac{[f^*]_{\mathcal{B}}^2}{m} \mathbb{E}_{\mu} \big[ \|x\|^2 \big] + [f^*]_{\mathcal{B}}^2 \big( \mathbb{E}_{\mu} \|x\| + \sigma^2 \big) \frac{\log n}{\sqrt{n}} \\ &+ \lambda \, [f^*]_{\mathcal{B}} \bigg). \end{split}$$



- Comparison with the previous result ([EMW19]).
  - We allow for general sub-Gaussian rather than compactly supported data distributions.
  - We do not control the magnitude of the bias variables.
  - Our results apply to l<sup>2</sup>-loss, which is neither globally Lipschitz-continuous nor bounded.
  - In a limiting regime, we characterize how the empirical risk minimizers interpolate in the region where no data is given by proving uniform convergence to a minimum norm interpolant.
- Minimum norm interpolant is not unique.

$$C\left(\frac{[f^*]_{\mathcal{B}}^2}{m} \mathbb{E}_{\mu}\left[\|x\|^2\right] + [f^*]_{\mathcal{B}}^2 \left(\mathbb{E}_{\mu}\|x\| + \sigma^2\right) \frac{\log n}{\sqrt{n}} + \lambda \left[f^*\right]_{\mathcal{B}}\right).$$

- 1/*m* term comes from the risk competitor (a 'good' Two-Layer ReLU network approximator need not be an ERM).
- $\log n/\sqrt{n}$  term comes from sub-Gaussian condition and Rademacher Complexity of Two-Layer ReLU neural networks.
- $\lambda$  term comes from the weight decay regularizer.
- Dependency on the dimension is implicit in  $\mathbb{E}_{\mu} ||x||$  and  $\sigma$  terms (and it is 'not' sharp).



- There is no guarantee that a training algorithm (often a 'local' algorithm) finds a 'global' ERM.
- When the set of minimum norm interpolants is known, we can compare numerical solutions to theoretical predictions to figure out how optimization algorithms work.
  - Examples of known minimum norm interpolants:
    - Convex data in one dimension.
    - Radially symmetric bump functions in odd dimensions.

# Convex data in one dimension

In 1d, any convex function is a minimum norm interpolant of convex data.

• Consider  $f^*(x) = |x|$  with data given for 1 < |x| < 2.



Small initialization and/or regularization lead to minimum norm bias for all optimization algorithms we studied.

Park, Pelakh, Wojtowytsch (TAMU, ISU, Pitt)

For radially symmetric 'bump function' data

$$f(0) = 1$$
 and  $||x||_2 \ge 1 \Rightarrow f(x) = 0$ 

there exists a *unique* radially symmetric minimum norm interpolant for odd dimensions (but there may be solutions without radial symmetry).



- All algorithms (SGD, SGD+Momentum, Adam) find a solution with the correct radial average shape without regularization (left).
- Adam exhibits the lowest degree of symmetry (middle).
- Adam has by far the highest value for the norm of the weights (right).

: Adam has a coordinate-wise update, unlike SGD (+Momentum).

$$g_{i} \leftarrow \partial f / \partial \theta_{i}$$

$$m_{i} \leftarrow \beta_{1} m_{i} + (1 - \beta_{1}) g_{i}$$

$$v_{i} \leftarrow \beta_{2} v_{i} + (1 - \beta_{2}) g_{i}^{2}$$

$$\theta_{i} \leftarrow \theta_{i} - \alpha \left(\frac{m_{i}}{1 - \beta_{1}^{t}}\right) / \left(\sqrt{\frac{v_{i}}{1 - \beta_{2}^{t}}} + \epsilon\right)$$

Figure 1: Adam updates. Element-wise squaring and re-scaling steps of Adam depend on coordinates.

As in this example, our theoretical results can be used to empirically demonstrate implicit bias of optimization algorithms.



- Obtained convergence of Two-Layer ReLU neural network ERMs with a rate for unbounded data and unbounded, non-Lipschitz loss.
- Proved locally uniform convergence to a minimum norm interpolant (no rate), esepcially even away from the support of the data.
- Demonstrated that known minimum norm interpolants can be used to study implicit bias in optimization.
- In several settings, empirically demonstrated implicit bias towards minimum norm solutions without regularization – large initialization exhibits less such bias.



## • Generalizing & Sharpening the bound.

- Different activations.
- Sharper rate for different norm (e.g.  $L^{\infty}(\mu)$  norm)?





This work was partially supported by the NSF DMS-2210689.

1 1

# Thank You!

Park, Pelakh, Wojtowytsch (TAMU, ISU, Pitt)

Minimum norm interpolation by perceptra

イロト イボト イヨト イヨト

Э



- Weinan E, Chao Ma, and Lei Wu, A priori estimates of the population risk for two-layer neural networks, Communications in Mathematical Sciences 17 (2019), no. 5, 1407–1425.
- Weinan E and Stephan Wojtowytsch, *Representation formulas and pointwise properties for barron functions*, 2021.
- Shai Shalev-Shwartz and Shai Ben-David, *Understanding machine learning: From theory to algorithms*, Cambridge university press, 2014.
- Stephan Wojtowytsch, *Optimal bump functions for shallow relu networks: Weight decay, depth separation and the curse of dimensionality,* arXiv preprint arXiv:2209.01173 (2022).

# Appendices

Park, Pelakh, Wojtowytsch (TAMU, ISU, Pitt)

Minimum norm interpolation by perceptra

イロト イボト イヨト イヨト

э



## Theorem (Convergence Theorem)

If m and  $\lambda$  scale with n as

$$\frac{\log n}{\sqrt{n}} \ll \lambda \ll 1, \qquad \frac{1}{m} \ll \lambda,$$

then almost surely over the choice of data points,  $f_n$  converges to  $f_\infty$  (1) in  $L^p(\mu)$  for  $p < \infty$  and (2) uniformly on compact subsets of  $\mathbb{R}^d$ , where  $f_\infty \equiv f^* \mu$ -almost everywhere and  $[f_\infty]_{\mathcal{B}} \leq [f^*]_{\mathcal{B}}$ . Also, with probability  $1 - 1/n^2$ :

$$\begin{aligned} \|f_{(a,W,b)_n} - f^*\|_{L^2(\mu)}^2 &\leq C \bigg( \frac{[f^*]_{\mathcal{B}}^2}{m} \mathbb{E}_{\mu} \big[ \|x\|^2 \big] + [f^*]_{\mathcal{B}}^2 \big( \mathbb{E}_{\mu} \|x\| + \sigma^2 \big) \frac{\log n}{\sqrt{n}} \\ &+ \lambda \, [f^*]_{\mathcal{B}} \bigg). \end{aligned}$$

# TM | TEXAS A&M

# • $L^{p}(\mu)$ -convergence:

- Rademacher complexity of Two-Layer ReLU networks with bounded weights (but not biases)
- Concentration inequalities to bound the magnitude of observed data (with high probability)
- **③** 1, 2  $\Rightarrow$  generalization bound with high probability.
- O Direct approximation theorem to construct a risk competitor.
- Q. 3, 4 ⇒ L<sup>2</sup>(µ) bound ≤ (ERM risk competitor) + (risk competitor f\*). The first term is controlled by 3. The second term is controlled from 4.
- **(**) For  $p \neq 2$ : Interpolation using the a priori Lipschitz bound from regularization.
- Ø Minimum norm interpolation (via Γ-convergence):
  - lim inf-inequality: Compact embedding theorem,  $L^2(\mu)$ -bound, Generalization bound.
  - lim sup-inequality: Direct approximation theorem and concentration for risk competitor.



# Definition (Rademacher Complexity)

Let  $S_n = \{x_1, \ldots, x_n\}$  be a set of points in  $\mathbb{R}^d$  (a data sample) and  $\mathcal{F}$  a real-valued function class. We define the empirical Rademacher complexity of  $\mathcal{F}$  on the data sample as

$$\widehat{\mathsf{Rad}}(\mathcal{F}; S_n) = \mathbb{E}_{\epsilon} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \epsilon_i f(x_i) \right]$$

where  $\epsilon_i$  are iid random variables which take the values  $\pm 1$  with equal probability  $\frac{1}{2}$ . The population Rademacher complexity is defined as

$$\mathsf{Rad}_n(\mathcal{F}) = \mathbb{E}_{\mathcal{S}_n \sim \mu^n} \big[ \widehat{\mathsf{Rad}}(\mathcal{F}; \mathcal{S}) \big],$$

i.e. as the expected empirical Rademacher complexity over a set of n iid data points.



Consider the function classes  $\mathcal{F}_Q$  and  $\mathcal{F}_Q(R)$ :

$$\mathcal{F}_{Q} = \overline{\operatorname{conv}\left\{a\left(\sigma(w \cdot x + b) - \sigma(b)\right) : a^{2} + \|w\|^{2} \le 2Q\right\}}$$

$$\mathcal{F}_Q(R) = \operatorname{conv}\left\{ a\left(\sigma(w \cdot x + b) - \sigma(b)\right) : a^2 + \|w\|^2 \le 2Q, |b| \le \sqrt{Q} R \right\}.$$

#### Lemma

$$\widehat{\mathsf{Rad}}(\mathcal{F}_Q, S_n) \leq \frac{\left(1 + 3\sqrt{2}\right)Q}{\sqrt{n}} \max_{1 \leq i \leq n} \|x_i\|.$$

If in addition  $\mu$  is a  $\sigma^2$  sub-Gaussian distribution in  $\mathbb{R}^d$ . Then for all  $n \ge 2$ 

$$\operatorname{\mathsf{Rad}}(\mathcal{F}_Q) \leq (1+3\sqrt{2})Q\left(\frac{\mathbb{E}_{x\sim\mu}[\|x\|]}{\sqrt{n}} + \sigma\sqrt{2\frac{\log n}{n}}\right).$$

Park, Pelakh, Wojtowytsch (TAMU, ISU, Pitt)

Some techniques for this calculation:

- The extreme points of  $\sup_{\mathcal{F}_Q} \sum_i \epsilon_i f(x_i)$  are achieved in the boundary of the convex hull (i.e. single width neural network).
  - : Combining the facts that (1) The functional  $f \mapsto \sum_{i=1}^{n} \epsilon_i f(x_i)$  is a continuous linear functional, and (2)  $\mathcal{F}_Q$  is a compact set in  $C^0(\mathcal{K})$  and  $L^2(\mu)$ .

•  $\widehat{\operatorname{Rad}}(\mathcal{F}_Q; S_n) = \widehat{\operatorname{Rad}}(\mathcal{F}_Q(R); S_n).$ 

• : if  $|b| \ge ||w|| R$ , then  $\sigma(w \cdot x + b) - \sigma(b) = \sigma(sgn(b))w \cdot x \Rightarrow$ substitute the cases  $|b| \ge ||w||R$  to |b| = ||w||R. • Split the variation by the following:

$$\mathbb{E}_{\epsilon} \left[ \sup_{\substack{a^{2}+\|w\|^{2} \leq Q, \ |b| \leq \|w\|R \\ |a|=\|w\| \leq \sqrt{Q}, \ |b| \leq \sqrt{Q}R}} \sum_{i=1}^{n} \epsilon_{i} a \left( \sigma(w \cdot x_{i}+b) - \sigma(b) \right) \right]$$

$$\leq \mathbb{E}_{\epsilon} \left[ \sup_{\substack{|a|=\|w\| \leq \sqrt{Q}, \ |b| \leq \sqrt{Q}R \\ i}} \left( \left| \sum_{i} \epsilon_{i} a \sigma(w \cdot x_{i}+b) \right| + \left| \sum_{i} \epsilon_{i} a \sigma(b) \right| \right) \right]$$

- First term bound:
  - ReLU: 1-Lipschitz ⇒ Contraction Lemma for Rademacher complexity ⇒ Can bound by Rademacher complexity of the class of linear functions on Hilbert space (We get max<sub>i</sub> ||x<sub>i</sub>|| term here).
- Second term bound:
  - Use ReLU is 1-Lipschitz again and bound on  $\mathbb{E}|\sum_i \epsilon_i|$ .
- For population quantity, use the concentration of  $\max_i ||x_i||$  to  $\mathbb{E}||x||$ , due to the sub-Gaussian condition (We get  $\log n/\sqrt{n}$  term here).

A slight modification of the previous Lemma leads to Rademacher complexity of general Barron functions with controlled bias.

Corollary (RC of Two-Layer ReLU)

Let

$$\mathcal{F}_{A,Q} := \{f \in \mathcal{B} : [f]_{\mathcal{B}} \leq Q, |f(0)| \leq A\}.$$

Under the same conditions as the above Lemma, we have

$$\mathsf{Rad}(\mathcal{F}_{A,Q}) \leq \left(1 + 3\sqrt{2}\right) Q\left(\frac{\mathbb{E}_{x \sim \mu}\left[\|x\|\right]}{\sqrt{n}} + \sigma \sqrt{2\frac{\log n}{n}}\right) + \frac{A}{\sqrt{n}}$$

 $\Rightarrow$  Rademacher complexity we obtained enable us to obtain a generalization bound.

#### Corollary (Generalization bound)

Let

$$\widehat{\mathcal{R}}_n(f) = \frac{1}{n} \sum_{i=1}^n |f(X_i) - f^*(X_i)|^2, \qquad \mathcal{R}(f) = \mathbb{E}_{x \sim \mu} [|f(x) - f^*(x)|^2].$$

If  $f^*$  satisfies  $|f^*(x) - f^*(0)| \le B_1 + B_2 ||x|| \mu$ -almost everywhere, then with probability at least  $1 - 2\delta$ ,

$$\sup_{f-f^*(0)\in\mathcal{F}_{A,Q}} \left(\mathcal{R}(f) - \widehat{\mathcal{R}}_n(f)\right) \le C^* \left( \left(Q + B_2\right) \left(\mathbb{E}_{x \sim \mu} \|x\| + \sigma^2 + 1\right) + A + B_1 \right)^2 \frac{\log(n/\delta)}{\sqrt{n}}$$

Park, Pelakh, Wojtowytsch (TAMU, ISU, Pitt)

・ 何 ト ・ ヨ ト ・ ヨ ト

Proof techniques:

- Split  $\mathbb{E}_{\mu}[(f(x) f^*(x))^2]$  to  $\mathbb{E}_{\mu}[(f(x) - f^*(x))^2 \mathbb{1}_{\|x\| \le R}] + \mathbb{E}_{\mu}[(f(x) - f^*(x))^2 \mathbb{1}_{\|x\| > R}].$
- First term: Regard it as using bounded Lipschitz loss ⇒ Apply canonical method of obtaining generalization bound from Rademacher complexity (See [SSBD14] Thm 26.5.).
- Second term: Use the fact  $|f(x) f^*(x)| \le |f(x) f^*(0)| + |f^*(x) f^*(0)| \le (A + B_1) + (Q + B_2)||x||$  and sub-Gaussian properties of ||x||.

# TEXAS A&M

# Theorem (Direct approximation, [Woj22] Prop. 2.6.)

Let  $f \in \mathcal{B}$  and  $\mu$  a measure on  $\mathbb{R}^d$  with finite second moments. Then for any  $m \in \mathbb{N}$  there exist  $c \in \mathbb{R}$  and  $(a_i, w_i, b_i) \in \mathbb{R} \times \mathbb{R}^d \times \mathbb{R}$  such that

$$\begin{split} \sum_{i=1}^m a_i^2 + \|w_i\|^2 &\leq [f]_{\mathcal{B}}, \\ \left\| f - c - \sum_{i=1}^m a_i \sigma(w_i^T x + b_i) \right\|_{L^2(\mu)} &\leq \frac{2[f]_{\mathcal{B}}}{\sqrt{m}} \sup_{\|w\|=1} \sqrt{\int_{\mathbb{R}^d} |w^T x|^2 \, \mathrm{d}\mu_x}. \end{split}$$

• Given  $f^*$ , we can obtain  $f_{\tilde{\theta}}$  from the direct approximation theorem, which we call a risk competitor.



### Theorem ( $L^2$ -convergence)

Let  $\hat{\theta} \in \operatorname{argmin}_{\theta} \widehat{\mathcal{R}}_{n,m,\lambda}(\theta)$ . If  $\delta \geq e^{-n}$ , and  $f^* \in \mathcal{F}_{Q^*}$ , then with probability at least  $1 - 4\delta$  over the choice of random points  $x_1, \ldots, x_n$  we have

$$\mathcal{R}(f_{\hat{\theta}}) \leq C\left(\frac{(Q^*)^2}{m} \left(\mathbb{E}\big[\|x\|^2\big]\right) + \lambda Q^* + Q^* \left(\mathbb{E}\|x\| + \sigma^2 + [f^*]_{\mathcal{B}}\right) \frac{\log(n/\delta)}{\sqrt{n}}\right)$$

up to higher order terms in the small quantities  $(\lambda m)^{-1}$ ,  $m^{-1}$ ,  $n^{-1/2} \log n$ .

• • = • • = •

Idea of proof:

Note the following:

$$\begin{split} \mathcal{R}(f_{\hat{\theta}}) &= \widehat{\mathcal{R}}_n(f_{\hat{\theta}}) + \mathcal{R}(f_{\hat{\theta}}) - \widehat{\mathcal{R}}_n(f_{\hat{\theta}}) \\ &\leq \widehat{\mathcal{R}}_{n,m,\lambda}(\hat{\theta}) + \mathcal{R}(f_{\hat{\theta}}) - \widehat{\mathcal{R}}(f_{\hat{\theta}}) \\ &\leq \widehat{\mathcal{R}}_{n,m,\lambda}(\widetilde{\theta}) + \mathcal{R}(f_{\hat{\theta}}) - \widehat{\mathcal{R}}_n(f_{\hat{\theta}}) \end{split}$$

- First term in 1 is directly bounded using direct approximation theorem.
- Second term: use generalization bound with suitable choice of Q and A.
  - Q:  $[f_{\hat{\theta}}]_{\mathcal{B}} \leq \frac{1}{\lambda} \widehat{\mathcal{R}}_{n,m,\lambda}(\hat{\theta}) \leq \frac{1}{\lambda} \widehat{\mathcal{R}}_{n,m,\lambda}(\widetilde{\theta}) = [f^*]_{\mathcal{B}} + O((\lambda m)^{-1})$ , which implies we can use  $Q = C[f^*]_{\mathcal{B}}$
  - A: Use the fact that Barron function is  $[\cdot]_{\mathcal{B}}$ -Lipschitz and apply the above.

# TEXAS A&M

# Corollary (L<sup>p</sup>-convergence)

Let  $p \in [1,\infty]$  and  $\hat{\theta}$  is ERM. Then there exists a constant  $\tilde{C} > 0$  depending on  $\mathbb{E}||x||, \mathbb{E}[||x||^2], \sigma^2$  and p such that

$$\|f_{\hat{\theta}} - f^*\|_{L^p(\mu)} \leq \tilde{C} \left(\widehat{\mathcal{R}}_{n,m,\lambda}(\hat{\theta})^{1/2} + [f^*]_{\mathcal{B}}\right)^{1-1/p} \|f_{\hat{\theta}} - f^*\|_{L^2(\mu)}^{1/p}.$$

- p < 2: From the fact  $L^2(\mu)$  embeds continuously into  $L^p(\mu)$ .
- p>2: Apply the following fact with  $g=f_{\hat{\theta}}-f^*$ :
  - if g is a measurable function which satisfies  $|g(x)| \leq C_g(1+\|x\|)$  for some  $C_g > 0$ , then

$$\|g\|_{L^p(\mu)}^{
ho} = \mathbb{E}ig[g \cdot g^{
ho-1}ig] \leq \mathbb{E}ig[g^2ig]^{1/2} \mathbb{E}ig[g^{2(
ho-1)}ig]^{1/2} = \|g\|_{L^2}\|g\|_{L^{2(
ho-1)}}^{
ho-1}.$$

• For  $\|f_{\hat{\theta}} - f^*\|_{L^{2(p-1)}}$ , we use the following from the Lipschitz condition:

$$\|f_{\hat{\theta}} - f^*\|_{L^{2(p-1)}(\mu)} \leq C\left(|f_{\hat{\theta}} - f^*|(0) + [f_{\hat{\theta}} - f^*]_{\mathcal{B}}\right).$$

- Bound of the first term was already derived as R
  <sub>n,m,λ</sub>(θ)<sup>1/2</sup> + C[f\*]<sub>B</sub> in L<sup>2</sup>(μ) convergence analysis (when figuring out A in generalization bound).
- $[f_{\hat{\theta}} f^*]_{\mathcal{B}} \leq [f_{\hat{\theta}}]_{\mathcal{B}} + [f^*]_{\mathcal{B}} \leq \widehat{\mathcal{R}}_{n,m,\lambda}(\hat{\theta}) + [f^*]_{\mathcal{B}} \lesssim \widehat{\mathcal{R}}_{n,m,\lambda}(\hat{\theta})^{1/2} + [f^*]_{\mathcal{B}}.$



## • $L^{p}(\mu)$ -convergence: Done!

- Rademacher complexity of Two-Layer ReLU networks with bounded weights (but not biases)
- Concentration inequalities to bound the magnitude of observed data (with high probability)
- $\ \, \textbf{31, 2} \Rightarrow \textbf{generalization bound with high probability.}$
- **O** Direct approximation theorem to construct a risk competitor.
- Q. 3, 4 ⇒ L<sup>2</sup>(µ) bound ≤ (ERM risk competitor) + (risk competitor f\*). The first term is controlled by 3. The second term is controlled from 4.
- For p > 2: Interpolation using the a priori Lipschitz bound from regularization.
- Ø Minimum norm interpolation (via Γ-convergence): Next Step!
  - lim inf-inequality: Compact embedding theorem,  $L^2(\mu)$ -bound, Generalization bound.
  - lim sup-inequality: Direct approximation theorem and concentration for risk competitor.

TEXAS A&M

A concept from the calculus of variation that is useful for the convergence of minimization problems.

## Definition

Let (X, d) be a metric space and  $F_n, F : X \to \mathbb{R} \cup \{-\infty, \infty\}$  be functions. We say that  $F_n$  converges to F in the sense of  $\Gamma$ -convergence if two conditions are met:

- (lim inf-inquality) If  $x_n$  is a sequence in X and  $x_n \to x$ , then lim inf<sub> $n\to\infty$ </sub>  $F_n(x_n) \ge F(x)$ .
- ② (lim sup-inequality) For every  $x \in X$ , there exists a sequence  $x_n^* \in X$  such that  $x_n^* \to x$  and lim  $\sup_{n\to\infty} F_n(x_n^*) \leq F(x)$ .
  - Remark: Γ-convergence depends on the convergence of the base space *X*.

イロト イポト イヨト イヨト

Usefulness of  $\Gamma$ -convergence: Guarantees an empirical minimizer converging to a population minimizer (but without explicit rate).

#### Lemma

Assume that  $F_n \to F$  in the sense of  $\Gamma$ -convergence,  $\epsilon_n \to 0^+$  and  $x_n \in X$  is a sequence such that

$$F_n(x_n) \leq \inf_{x \in X} F_n(x) + \epsilon_n.$$

Assume that  $x_n \to x^*$ . Then  $F(x^*) = \inf_{x \in X} F(x)$ . In particular, if  $x_n$  is a minimizer of  $F_n$  and the sequence  $x_n$  converges, then the limit point is a minimizer of F.

・ 同 ト ・ ヨ ト ・ ヨ ト



#### • Convergence in the base space:

- Define  $f_k \xrightarrow{good} f$  if  $f_k \to f$  uniformly on compact sets and in  $L^2(\mu)$ .
- Define  $\theta_k \xrightarrow{good} f$  if  $f_{\theta_k} \xrightarrow{good} f$ .
- Γ-functional:

• 
$$F_n(\theta) := \widehat{\mathcal{R}}_{n,m_n,\lambda_n}(f_\theta)/\lambda_n$$
  
•  $F(f) = [f]_{\mathcal{B}}$  if  $f = f^* \ \mu - a.s.$  and  $+\infty$  o.w.

#### Theorem ( $\Gamma$ -convergence of the risk functional)

Given above constructions,  $\Gamma - \lim_{n \to \infty} F_n = F$  a.s. with respect to the notion of convergence  $\theta_k \xrightarrow{good} f$ .

 $\Rightarrow$  Since *F*'s minimizer is a minimum norm interpolant, the theorem gives ERM's convergence to a minimum norm interpolant.



lim inf-inequality:

• Strategy: Divide the case when  $f = f^* \mu - a.s.$  and not.

$$\liminf_{n\to\infty} F_n(\theta_n) \geq \liminf_{n\to\infty} R_{WD}(\theta_n) \geq \liminf_{n\to\infty} [f_{\theta_n}]_{\mathcal{B}} \geq [f]_{\mathcal{B}} = F(f)$$

where third inequality comes from lower semi-continuity of Barron semi-norm.

• 
$$f \neq f^* \mu - a.s.$$
: Show  $\liminf_n F_n(\theta_n) \ge F(f) = \infty$  for  $\forall \theta_n \xrightarrow{good} f$ :

$$\begin{split} F_n(\theta_n) &\geq \frac{\widehat{\mathcal{R}}_n(f_{\theta_n}) - \mathcal{R}(f_{\theta_n})}{\lambda_n} + \frac{\|f - f^*\|_{L^2(\mu)}^2 + \|f_{\theta_n} - f\|_{L^2(\mu)}^2}{\lambda_n} + [f_{\theta_n}]_{\mathcal{B}} \\ &\geq O\left(\frac{\log n}{\lambda_n \sqrt{n}}\right) + \frac{\|f - f^*\|_{L^2(\mu)}^2}{\lambda_n} + [f_{\theta_n}]_{\mathcal{B}} \to \infty. \end{split}$$



lim sup-inequality:

- Strategy: Only one sequence is sufficient
  - $\Rightarrow$  for given f take  $\hat{\theta}_n$  from Direct approximation.

• 
$$f = f^* \mu - a.s.$$
:

$$F_n(\tilde{ heta}_n) \leq rac{C}{\lambda_n m_n} \left(1 + rac{\log n}{\sqrt{n}}\right) + [f]_{\mathcal{B}} \to [f]_{\mathcal{B}} = F(f).$$

•  $f \neq f^* \mu - a.s.$ : Since  $F(f) = \infty$ , any sequence  $\theta_n$  satisfy  $F_n(\theta_n) \leq \infty = F(f)$ .